NFX24-MFT-S - Damper Actuator

Modulating, Spring Return, 24 V, Multi-Function Technology®

Torque min. 90 in-lb, Control 2 to 10 VDC (DEFAULT), Feedback 2 to 10 VDC (DEFAULT)

Application

For fail-safe, modulating control of dampers in HVAC systems. Actuator sizing should be done in accordance with the damper manufacturer's specifications. A feedback signal is provided for position indication.

Default/Configuration

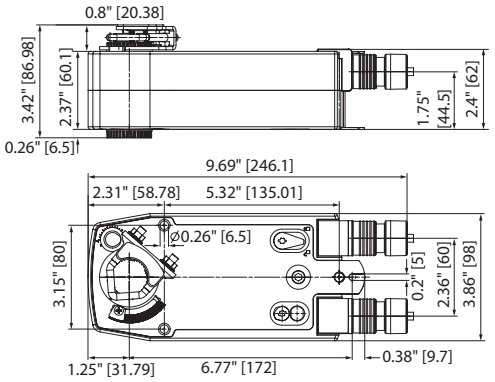
Default parameters for 2 to 10 VDC applications of the NF..-MFT actuator are assigned during manufacturing. If required, custom versions of the actuator can be ordered. The parameters are variable and can be changed by three means: Factory pre-set or custom configuration, set by the customer using PC-Tool software or the handheld ZTH US.

Operation

The NF..24-MFT actuator provides 95° of rotation and is provided with a graduated position indicator showing 0° to 95°. The actuator will synchronize the 0° mechanical stop or the physical damper or valve mechanical stop and use this point for its zero position during normal control operations. A unique manual override allows the setting of any actuator position within its 95° of rotation with no power applied. This mechanism can be released physically by the use of a crank supplied with the actuator. When power is applied the manual override is released and the actuator drives toward the fail-safe position. The actuator uses a brushless DC motor which is controlled by an Application Specific Integrated Circuit (ASIC) and a microprocessor. The microprocessor provides the intelligence to the ASIC to provide a constant rotation rate and to know the actuators's exact position. The ASIC monitors and controls the brushless DC motor's rotation and provides a Digital Rotation Sensing (DRS) function to prevent damage to the actuator in a stall condition. The position feedback signal is generated without the need for mechanical feedback potentiometers using DRS. The actuator may be stalled anywhere in its normal rotation without the need of mechanical end switches. The NF..24-MFT is mounted directly to control shafts up to 1.05" diameter by means of its universal clamp and anti-rotation bracket. A crank arm and several mounting brackets are available for damper applications where the actuator cannot be direct coupled to the damper shaft. The spring return system provides minimum specified torque to the application during a power interruption. The NF..24-MFT actuator is shipped at +5° (5° from full fail-safe) to provide automatic compression against damper gaskets for tight shut-off.

Technical Data	
Power Supply	24 VAC±20%, 50/60Hz, 24 VDC+20%/-10%
Power Consumption Running	6.5 W
Power Consumption Holding	3 W
Transformer Sizing	9 VA (class 2 power source)
Shaft Diameter	1/2" to 1.05" round, centers on 1/2" and 3/4" with insert, 1.05" without insert
Electrical Connection	(2) 3 ft [1 m], 10 ft [3 m] or 16 ft [5 m] 18 GA appliance cables with or without 1/2" conduit connectors
Overload Protection	electronic throughout 0° to 95° rotation
Electrical Protection	actuators are double insulated
Operating Range Y	2 to 10 VDC, 4 to 20 mA w/ ZG-R01 (500 Ω, 1/4 W resistor), variable (VDC, PWM, floating point, on/off)
Input Impedance	100 k Ω for 2 to 10 VDC (0.1 mA), 500 Ω for 4 to 20 mA, 1500 Ω for PWM, floating point and On/Off
Feedback Output U	2 to 10 VDC, 0.5 mA max, VDC variable
Angle of Rotation	95° (adjustable with mechanical end stop, 35° to 95°)
Torque	90 in-lbs [10 Nm] minimum
Direction of Rotation (Motor)	reversible with built-in switch
Direction of Rotation (Fail-Safe)	reversible with CW/CCW mounting
Position Indication	visual indicator, 0° to 95° (0° is full spring return position)
Manual Override	5 mm hex crank (3/16" Allen), supplied
Running Time (Motor)	150 sec (default), variable (40 to150 sec)
Running Time (Fail-Safe)	<20 sec @ -4°F to 122°F [-20°C to 50°C], < 60 sec @ -22°F [-30°C]
Angle of Rotation Adaptation	Off (default)
Override Control	min. position = 0% , mid. Position = 50% , max. position = 100% (Default)
Humidity	max. 95% RH non-condensing
Ambient Temperature Range	-22°F to +122°F [-30°C to +50°C]
Storage Temperature Range	-40°F to +176°F [-40°C to +80°C]
Housing	NEMA 2, IP54, UL enclosure type 2
Housing Material	zinc coated metal and plastic casing
Agency Listings†	cULus acc. to UL60730-1A/-2-14, CAN/CSA E60730-1:02, CE acc. to 2004/108/EC and 2006/95/EC
Noise Level (Motor)	≤40 dB (A) @ 150 sec, run time dependent
Noise Level (Fail-Safe)	<62 dB (A)
Servicing	maintenance free
Quality Standard	ISO 9001
Weight	4.4 lb [2 kg]
Auxiliary Switch	2 x SPDT, 3A resistive (0.5A inductive) @ 250 VAC, one set at +10°, one adjustable 10° to 90°

Dimensions (Inches[mm])



*Variable when configured with MFT options.
†Rated Impulse Voltage 800V, Type of Action 1.AA.B, Control Pollution Degree 3.

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Auxiliary Switch	2 x SPDT, 3A resistive (0.5A inductive) @ 250 VAC, one set at +10°, one adjustable 10° to 90°

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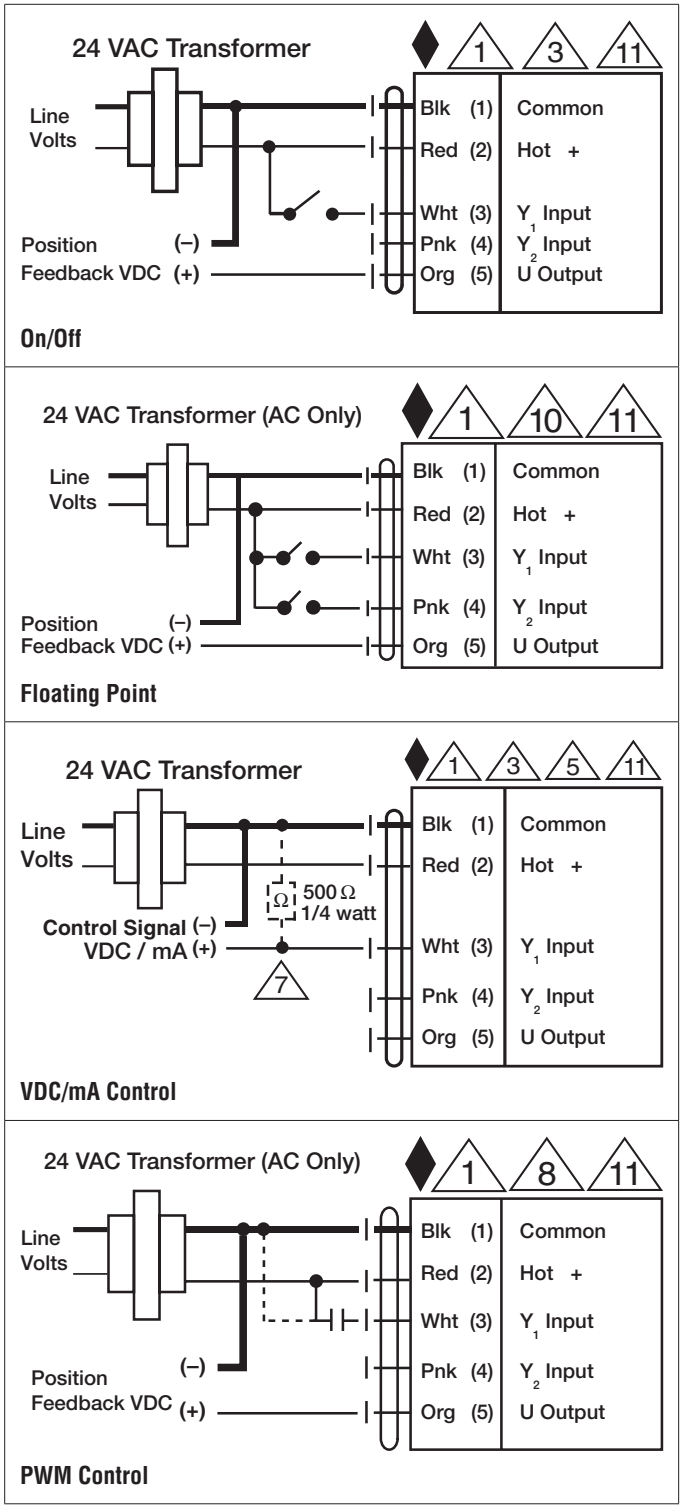
Accessories	
AF-P	Anti-rotation bracket AF/NF.
AV8-25	9.8” shaft extension for 5/16” to 1” diameter shafts.
IND-AFB	AFB(X)/NFB(X) position indicator.
K7-2	Standard AFB(X)/NFB(X) clamp (1/2” to 1.05”).
KG10A	Ball joint for 3/8” diameter rod, zinc plated.
KG8	Ball joint for 5/16” diameter rod, 90°, galvanized steel.
KH10	Univ. crankarm, slot 21/64” w, for 9/16” to 1” dia. shafts.
KH12	Univ. crankarm, slot 21/64” w, for 3/4” to 1” dia. shafts.
KH8	Univ. crankarm,slot 21/64” w,for 3/8” to 11/16” dia. shafts.
KH-AFB	AFB(X)/NFB(X) crankarm (with 3/4” dia. shaft pass through).
SH10	Push rod for KG10A ball joint (36” L, 3/8” diameter).
SH8	Push rod for KG6 & KG8 ball joints (36” L, 5/16” diameter).
TOOL-06	8 mm and 10 mm wrench.
Z-AF	Classic AF/NF to AFB(X)/NFB(X) retrofit mounting bracket.
ZG-100	Univ. right angle bracket (17” H x 11-1/8” W x 6” base).
ZG-101	Univ. right angle bracket (13” H x 11” W x 7-7/16” base).
ZG-109	Right angle bracket for ZS-260.
ZG-110	Stand-off bracket for ZS-260.
ZG-118	AFB(X)/NFB(X) U bracket (5-7/8” H x 5-1/2” W x 2-19/32” D).
ZG-120	Jackshaft mounting bracket.
ZG-AFB	AFB(X)/NFB(X) crankarm adaptor kit.
ZG-AFB118	AFB(X)/NFB(X) crankarm adaptor kit.
ZG-DC1	Damper clip for damper blade, 3.5” width.
ZG-DC2	Damper clip for damper blade, 6” width.
ZG-JSA-1	1” diameter jackshaft adaptor (11” L).
ZG-JSA-2	1-5/16” diameter jackshaft adaptor (12” L).
ZG-JSA-3	1.05” diameter jackshaft adaptor (12” L).
ZS-100	Weather shield - galvaneal (13” L x 8” W x 6” D).
ZS-101	Base plate for ZS-100.
ZS-150	Weather shield - PC w/ foam seal (16” L x 8-3/8” W x 4” D).
ZS-260	Explosion proof housing.
ZS-300	NEMA 4X, 304 stainless steel enclosure.
ZS-300-5	NEMA 4X, 316L stainless steel enclosure.
ZS-300-C1	1/2” shaft adaptor, standard wtih ZS-300(-5).
ZS-300-C2	3/4” shaft adaptor for ZS-300(-5).
ZS-300-C3	1” shaft adaptor for ZS-300(-5).
Z-SF	20 piece Z-AF kit.
ADS-100	Analog to digital switch for modulating actuators.
IRM-100	Input rescaling module for modulating actuators.
MFT-P	Belimo MFT configuration software (hardware not included).
PS-100	Actuator power supply and control simulator.
PTA-250	Pulse width modulation interface for modulating actuators.
SGA24	Positioner control for modualting actuators (surface mount).
SGF24	Positioner control for modulating actuators (flush mount).
TF-CC US	Cable conduit connector, 1/2”.
UK24BAC	BACnet gateway module for up to 8 MFT actuators.
UK24LON	LON gateway module for up to 8 MFT actuators.
UK24MOD	MODbus gateway module for up to 8 MFT actuators.
ZG-R01	4 to 20 mA adaptor, 500Ω, 1/4 W resistor w 6” pigtail wires.
ZG-R02	50% voltage divider kit (resistors with wires).
ZG-SGF	Mounting plate for SGF.
ZG-X40	120 to 24 VAC, 40 VA transformer.
ZK2-GEN	Cable for ZTH US to actuators w/o diagnostics socket.
ZTH US	Handheld programming tool w/ ZK1-GEN, ZK2-GEN, ZK6-GEN.



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Typical Specification

Spring return control damper actuators shall be direct coupled type which require no crank arm and linkage and be capable of direct mounting to a jackshaft up to a 1.05" diameter. The actuator must provide modulating damper control in response to a 2 to 10 VDC or, with the addition of a 500Ω resistor, a 4 to 20 mA control input from an electronic controller or positioner. The actuators must be designed so that they may be used for either clockwise or counter clockwise fail-safe operation. Actuators shall use a brushless DC motor controlled by a microprocessor and be protected from overload at all angles of rotation. Run time shall be constant, and independent of torque. A 2 to 10 VDC feedback signal shall be provided for position feedback. Actuators shall be cULus listed and have a 5 year warranty, and be manufactured under ISO 9001 International Quality Control Standards. Actuators shall be as manufactured by Belimo.

Wiring Diagrams

WARNING! LIVE ELECTRICAL COMPONENTS!

During installation, testing, servicing and troubleshooting of this product, it may be necessary to work with live electrical components. Have a qualified licensed electrician or other individual who has been properly trained in handling live electrical components perform these tasks. Failure to follow all electrical safety precautions when exposed to live electrical components could result in death or serious injury.

Meets cULus requirements without the need of an electrical ground connection.

Apply only AC line voltage or only UL-Class 2 voltage to the terminals of auxiliary switches. Mixed or combined operation of line voltage/safety extra low voltage is not allowed.

(A) Actuators with appliance cables are numbered.

1 Provide overload protection and disconnect as required.

3 Actuators may also be powered by 24 VDC.

4 Two built-in auxiliary switches (2x SPDT), for end position indication, interlock control, fan startup, etc.

5 Only connect common to negative (-) leg of control circuits.

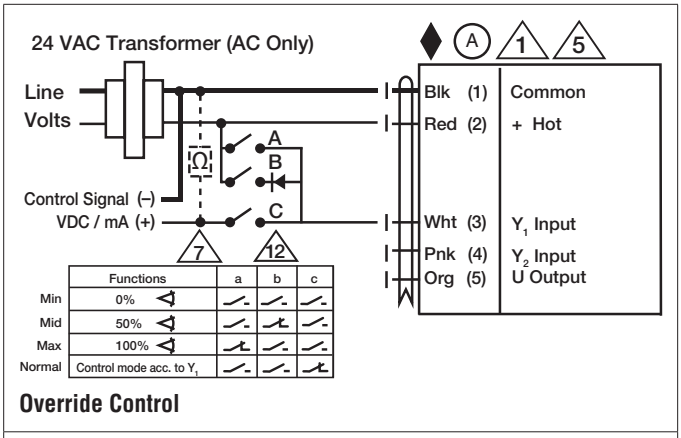
7 A 500 Ω resistor (ZG-R01) converts the 4 to 20 mA control signal to 2 to 10 VDC.

8 Control signal may be pulsed from either the Hot (Source) or Common (Sink) 24 VAC line.

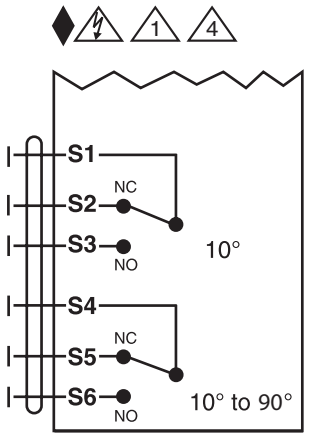
10 For triac sink the Common connection from the actuator must be connected to the Hot connection of the controller. Position feedback cannot be used with a triac sink controller; the actuator internal common reference is not compatible.

11 Actuators may be connected in parallel if not mechanically linked. Power consumption and input impedance must be observed.

12 IN4004 or IN4007 diode. (IN4007 supplied, Belimo part number 40155).



Override Control



Auxiliary Switches

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